

OPERATING INSTRUCTIONS E38A REV. 0

## Variable Reluctance Speed Sensor E38A



INDUSTRIAL SPEED SENSORS

## **Product ID**

	Type #	Product #	Drawing #	
	E38A	385Z-05356	113.703 Rev.1	
General				
Function	an inductive coil, and a per sensor face changes the m being induced in the coil. T speed of the moving target gap, geometry of target, ma	manent magnet. A fer nagnetic field strength, he frequency of the out the amplitude of the agnetic properties of ta own as passive or elect	sensors consist of an iron core, rous pole wheel passing the resulting in an AC voltage utput signal is proportional to the signal depends on speed, air arget material, and the electrica tromagnetic sensors, do not	
Technical data				
Coil properties	<ul> <li>Inductance @ 1 kHz: 17</li> <li>Resistance: 850 Ohm ±</li> <li>Magnet polarity: north p</li> <li>Pole piece: diameter 2.7</li> </ul>	10% ole towards front face		
Polarity	Upon approach of ferrous r	metal, the signal pin is	positive with respect to GND.	
Signal output	The signal frequency is proportional to the target speed. The signal amplitude shown in the figure is valid for a load of 100 kOhm, and is affected by air gap, target geometry and material. It is also proportional to the linear speed of the teeth.			
	Typical output voltage (reference speed 10 m/s, 100 kOhm load)			
	100.00 East and the set of the s	1.5 2 2.5 Air gap (mm)		
Frequency range	Up to 20 kHz, lower limit depending on application			
Housing	3/8"-24 UNF-2A, tightening torque: max. 10 Nm			
Connection	Connector: M12x1 thread, 4 pins, black			
Protection	Sensor head: IP68 Connector: IP67			
Insulation	Housing and electronics galvanically isolated (Test: 500 V, 50 Hz for 1 minute)			
Pole wheel	<ul> <li>Prerequisite: Toothed wheel of a ferrous material (e.g. Steel 1.0036).</li> <li>Optimal performance with <ul> <li>Involute gear</li> <li>Tooth width &gt; 10 mm</li> <li>Side offset &lt; 0.2 mm</li> <li>Eccentricity &lt; 0.2 mm</li> </ul> </li> </ul>			
	<ul> <li>Eccentricity &lt; 0.2 mm</li> </ul>			



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pole wheel	trigger level. See figure.		
Electromagnetic compatibility (EMC)	Please contact Jaquet for further details.		
Vibration & shock immunity	Jaquet Greenline sensors are approved for rough environments. Please contac Jaquet for further details.		
Operating temperature	-40°C125°C		
Further Information			
Safety	All mechanical installations must be carried out by an expert. General safety requirements have to be met.		
Installation	The sensor has to be aligned to the pole wheel according to the sensor draw independent of its rotational orientation. Deviations in positioning may affect performance and decrease the noise immunity of the sensor. During installat the smallest possible pole wheel to sensor gap should be set. The gap shou however be set to prevent the face of the sensor ever touching the pole whe A sensor should be mounted with the middle of the face side over the middle the pole wheel. Dependent upon the wheel width, a certain degree of axial movement is permissible. However, the middle of the sensor must be at minimum in a distance of 3 mm from the edge of the pole wheel under all operating conditions. A solid and vibration free mounting of the sensor is important. Eventual sens vibration relative to the pole wheel can induce additional output pulses. The sensors are insensitive to oil, grease etc. and can be installed in arduou conditions.		
Maintenance	Product cannot be repaired.		
Transport	Product must be handled with care to prevent damage of the front face.		
Storage	Product must be stored in dry conditions. The storage temperature corresponds to the operation temperature.		
Disposal	Product must be disposed of properly, it must not be disposed as domestic waste.		



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